**Publishing the same process**

**Managing multiple versions of the same process**

* In UiPath Studio, change the string in the **Message Box** activity from “Hello UiPath Orchestrator!” to “Hi World!”.
* Run the process to check if it displays the correct message on the screen.
* Click **Publish**.
* In Orchestrator, open the **Processes** page and navigate to **Packages**. The package list is displayed.
* Find the Orchestrator Hello World package, and click **View Versions**. Two versions of the package are displayed - an active and an inactive one. The active one is the one you started manually, and the inactive one is the one you have just published.
* Navigate back to the processes pane to check the versions and select the version.
* Select the one you want to use.

There is another way you can send a package to Orchestrator.

If the robot instance is not connected to Orchestrator, the package has to be uploaded manually.

* Publish a package in Studio. The package is sent to a local folder.
* Go to the **Packages** section in Orchestrator and click on **Upload.**The **Upload Package** window is displayed.
* Browse for the OrchestratorHelloWorld.nupkg file**,**which is saved in C:\ProgramData\UiPath\Packages by default.
* Click **Upload**to add the package to Orchestrator.

The process now contains all its versions listed in chronological order, from the first published one to the last.